

Electromagnetic solvers in 2D and 3D

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BOUT++ Workshop

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- Potential fields in reduced MHD models
- 2D direct solvers used in BOUT and BOUT++
- 2D iterative solvers in BOUT++ (using PETSc)
- Issues with 2D solvers

- 3D solvers and preliminary results
- Some different approaches

- Discussion

Drift-reduced fluid models usually formulated in terms of a vorticity

- Fluid velocity assumed to have form $\mathbf{v} = v_{\parallel}\mathbf{b} + \text{drifts}$
- Rather than evolving \mathbf{v} , solve for v_{\parallel} and a scalar vorticity $\omega = \mathbf{b} \cdot \nabla \times (m_i n_i \mathbf{v})$
- From either momentum or charge conservation $\nabla \cdot \mathbf{J} = 0$:

$$\frac{\partial}{\partial t} \nabla \cdot \left(\frac{m_i n}{B^2} \nabla_{\perp} \phi \right) = \nabla \cdot (\mathbf{J}_{\parallel} \mathbf{b}) + \nabla \cdot \mathbf{J}_{\text{dia}} + \text{Higher order terms}$$

with $\nabla_{\perp} = \nabla - \mathbf{b}\mathbf{b} \cdot \nabla$

- Inverting the operator $\nabla \cdot \left(\frac{m_i n}{B^2} \nabla_{\perp} \phi \right)$ to obtain the potential ϕ is a major part of the complexity and computational expense in a drift-reduced fluid simulation

In curvilinear coordinates the operator to be inverted is

$$\nabla \cdot \left(\frac{m_i n}{B^2} \nabla_{\perp} \phi \right) = \frac{1}{J} \frac{\partial}{\partial u^i} \left(J \frac{m_i n}{B^2} g^{ij} (\nabla_{\perp} \phi)_j \right)$$

- The Clebsch coordinate system $\mathbf{B} = \nabla\psi \times \nabla\alpha$ used in BOUT++ is non-orthogonal, since $\alpha =$ toroidal angle.
- This enables FFTs to be used, but $g^{ij} (\nabla_{\perp} \phi)_j \neq 0$ along \mathbf{B} direction.
- Drift ordering $k_{\parallel} \ll k_{\perp}$ is usually used to drop derivatives along \mathbf{B} .
- This reduces the number of dimensions to 2, reducing the computational difficulty.

2D inversion using FFTs

The standard BOUT++ coordinate system (inherited from BOUT)¹ uses toroidal angle ζ as one of its coordinates:

$$\begin{aligned}x &= \psi - \psi_0 & y &= \theta \\z &= \zeta - \int_{\theta_0}^{\theta} \nu(\psi, \theta) d\theta\end{aligned}$$

with $\nu(\psi, \theta) = \frac{\mathbf{B} \cdot \nabla \zeta}{\mathbf{B} \cdot \nabla \theta}$ is the local field-line pitch.

- In these coordinates equilibrium quantities and metric components are constant, so Fourier transforms can be used
- **But:** Only if we assume that the coefficient is constant in ζ

$$\frac{1}{J} \frac{\partial}{\partial u^i} \left(\underbrace{J \frac{m_i n}{B^2} g^{ij}}_{\text{Constant in } \zeta} (\nabla_{\perp} \phi)_j \right)$$

Commonly called the **Boussinesq approximation**

¹See coordinates manual for details

2D inversion using FFTs

In the Laplacian class implementations, the operator is expanded in a non-conservative form:

$$\nabla \cdot (\alpha \nabla_{\perp} \phi) = \omega \quad \rightarrow \quad \nabla_{\perp}^2 \phi + \frac{1}{\alpha} \nabla_{\perp} \alpha \cdot \nabla_{\perp} \phi = \omega / \alpha$$

which is solved by setting coefficients:

$$D \nabla_{\perp}^2 x + \frac{1}{C} \nabla_{\perp} C \cdot \nabla_{\perp} x = b$$

```
Laplacian* phiSolver = Laplacian::create();
```

```
phiSolver->setCoefD(1.0); // This is the default  
phiSolver->setCoefC(alpha);
```

```
Field3D phi = phiSolver->solve(omega / alpha);
```

Note: If any coefficients depend on z (ζ) then they are averaged

2D inversion using FFTs

The Laplacian operator can be written in terms of ψ derivatives as:

$$\begin{aligned}\nabla_{\perp}^2 &= (RB_{\theta})^2 \left[\frac{\partial^2}{\partial \psi^2} + \frac{B^2}{(RB_{\theta})^4} \frac{\partial^2}{\partial z^2} \right] \\ &+ \frac{1}{J} \frac{\partial}{\partial \psi} \left[J (RB_{\theta})^2 \right] \frac{\partial}{\partial \psi} - \frac{1}{J} \frac{\partial}{\partial y} \left(\frac{B_{\zeta}}{B_{\theta}^2 R} \right) \frac{\partial}{\partial z}\end{aligned}$$

Taking Fourier transforms in z ,

$$\frac{\partial}{\partial z} \rightarrow -ik_z$$

- For each toroidal mode k_z , these equations reduce to a second order equation in ψ (or x).
- These can be solved independently using efficient algorithms

2D inversion using FFTs: Implementation

The 1D equations in x are discretised using a 3-point stencil

- Tridiagonal system of equations

Boundary conditions need to be set on inner and outer x

- Zero value (the default)
- Zero gradient
- Decaying Laplacian approximation
- Cylindrical boundary condition
- ...

See `include/invert_laplace.hxx`

Set using a system of flags

```
phiSolver->setInnerBoundaryFlags (INVERT_DC_GRAD);  
phiSolver->setOuterBoundaryFlags (INVERT_AC_GRAD);
```

- Note the distinction between DC ($k_z = 0$) and AC ($k_z \neq 0$) components: $k_z = 0$ is a special case due to gauge invariance

The Boussinesq approximation can lead to non-conserved energy

- Solving equations for the shear Alfvén wave: Vorticity ω and electromagnetic potential A_{\parallel} , with auxiliary equations for the electrostatic potential ϕ and parallel current $j_{\parallel} = \mathbf{b}_0 \cdot \mathbf{j}$:

$$\begin{aligned}\frac{\partial \omega}{\partial t} &= \nabla \cdot (\mathbf{b}_0 j_{\parallel}) & \frac{\partial A_{\parallel}}{\partial t} &= -\mathbf{b}_0 \cdot \nabla \phi \\ \omega &= \nabla \cdot \left(\frac{m_i n}{B^2} \nabla_{\perp} \phi \right) & \nabla_{\perp}^2 A_{\parallel} &= -\mu_0 j_{\parallel}\end{aligned}$$

- This has a conserved energy

$$E = \frac{1}{2} \int dV \left[\frac{m_i n}{B^2} |\nabla_{\perp} \phi|^2 + \frac{1}{\mu_0} |\nabla_{\perp} A_{\parallel}|^2 \right]$$

Making the approximation

$$\nabla \cdot \left(\frac{m_i n}{B^2} \nabla_{\perp} \phi \right) \simeq \nabla \cdot \left(\underbrace{\frac{m_i n_0}{B^2}}_{\text{Axisymmetric, constant}} \nabla_{\perp} \phi \right)$$

modifies the conserved energy, but the approximation

$$\nabla \cdot \left(\frac{m_i n}{B^2} \nabla_{\perp} \phi \right) \simeq n \nabla \cdot \left(\frac{m_i}{B^2} \nabla_{\perp} \phi \right)$$

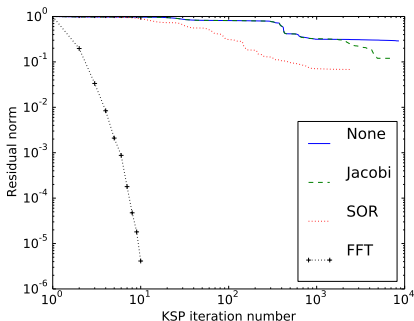
introduces an energy source

$$\frac{dE}{dt} = \int dV \left[\phi \frac{m_i}{B^2} \frac{\partial \nabla_{\perp} \phi}{\partial t} \cdot \nabla n \right]$$

→ Would like to remove the Boussinesq approximation

2D inversion using PETSc

- BOUT++ can use the PETSc library to solve these equations
- Contains a number of iterative schemes e.g. CG, GMRES, ...
- To find a solution efficiently, a preconditioner is needed



- See talk at 2013 workshop: bout2013.llnl.gov
- Examples: examples/blob2d
- Need to compile and configure with PETSc

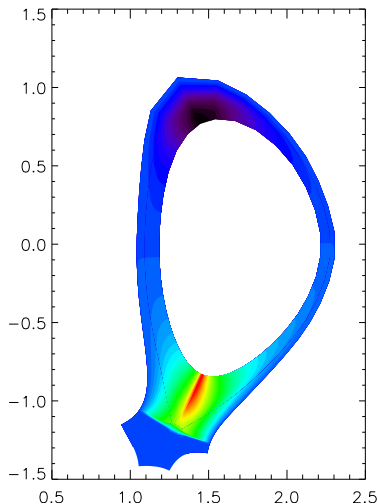
```
./configure --with-petsc
```

- 1 **Boundary conditions:** A separate boundary condition is imposed on each $x - z$ plane ($\psi - \zeta$ in most simulations). This may over-constrain the problem

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- 2 **Difficulty with $m = 0$ modes:** If z is toroidal angle, then the y (parallel; poloidal) derivatives cannot be neglected for the $n = 0, m = 1$ mode.
 - Becomes particularly problematic in X-point geometry
 - Switching to using planes in $\psi - \theta$ helps, but loses the ability to take Fourier transforms and reduce to 1-D problem.

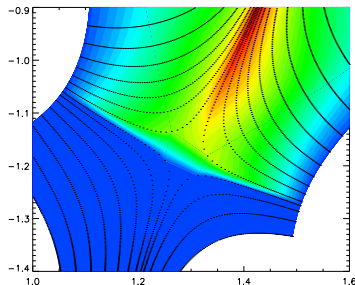
Numerical methods - Global X-point geometry

- The standard method previously used has problems solving for global-scale electric fields (e.g. $n = 0$) in X-point geometry



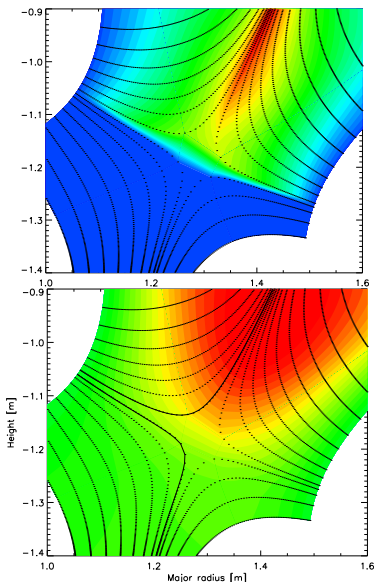
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- Neglect of “small” quantities can lead to unphysical solutions



Numerical methods - Global X-point geometry

- The standard method previously used has problems solving for global-scale electric fields (e.g. $n = 0$) in X-point geometry
- Neglect of “small” quantities can lead to unphysical solutions
- Efficient methods implemented to solve full 3D problem
- Should enable more realistic simulation of global X-point geometry



A big problem for all 3D simulations is **Fast timescales**: Parallel electron dynamics tends to make timesteps very small (\ll ion cyclotron time).

- How to include parallel Ohm's law, but remove these timescales?
- Preconditioning complicated by mixing of k_{\perp} and k_{\parallel} .
→ Multigrid methods?
- P.Tamain: Combining Ohm's law and Vorticity equation into 3D equation for ϕ
- Is there a better way?